

//Note: For the best effect, we suggest you view the program with the Source Insight software.

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//XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
//   Proram:          79676
//   Author:          XING TAI
//   Date:            2025
//   Rev:             1.0
//XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
//
//XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX

/*****
*****
*Header File
*****
*****/

#include "n32wb03x.h"
#include "image.h"

/*****EPD Resolution*****/                                     //EPD
Resolution Settings
#define GATES          250
#define SOURCES        128

#define EINK_SDA_PIN    GPIO_PIN_6
#define EINK_SDA_PORT   GPIOA
#define EINK_SCL_PIN    GPIO_PIN_8
#define EINK_SCL_PORT   GPIOB
#define EINK_NCS_PIN    GPIO_PIN_9
#define EINK_NCS_PORT   GPIOB
#define EINK_NDC_PIN    GPIO_PIN_1
#define EINK_NDC_PORT   GPIOB
#define EINK_RST_PIN    GPIO_PIN_2
#define EINK_RST_PORT   GPIOB
#define EINK_BUSY_PIN   GPIO_PIN_3
#define EINK_BUSY_PORT  GPIOB

#define SDA_H           GPIO_SetBits    (EINK_SDA_PORT,    EINK_SDA_PIN)
#define SDA_L           GPIO_ResetBits  (EINK_SDA_PORT,    EINK_SDA_PIN)
#define SCLK_H          GPIO_SetBits    (EINK_SCL_PORT,    EINK_SCL_PIN)
#define SCLK_L          GPIO_ResetBits  (EINK_SCL_PORT,    EINK_SCL_PIN)
#define nCS_H           GPIO_SetBits    (EINK_NCS_PORT,    EINK_NCS_PIN)
#define nCS_L           GPIO_ResetBits  (EINK_NCS_PORT,    EINK_NCS_PIN)
#define nDC_H           GPIO_SetBits    (EINK_NDC_PORT,    EINK_NDC_PIN)
#define nDC_L           GPIO_ResetBits  (EINK_NDC_PORT,    EINK_NDC_PIN)
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#define nRST_H          GPIO_SetBits    (EINK_RST_PORT,   EINK_RST_PIN)
#define nRST_L          GPIO_ResetBits  (EINK_RST_PORT,   EINK_RST_PIN)

#define SDA_LEVEL       GPIO_ReadInputDataBit(EINK_SDA_PORT, EINK_SDA_PIN)
#define BUSY_LEVEL      GPIO_ReadInputDataBit(EINK_BUSY_PORT, EINK_BUSY_PIN)

#define EINK_VOLO_PIN   GPIO_PIN_2
#define EINK_VOLO_PORT  GPIOA

#define EINK_VOL1_PIN   GPIO_PIN_3
#define EINK_VOL2_PORT  GPIOA

#define VDD_OFF         GPIO_ResetBits  (EINK_VDD_PORT,   EINK_VDD_PIN)
#define VDD_ON          GPIO_SetBits    (EINK_VDD_PORT,   EINK_VDD_PIN)

#define EINK_VDD_PIN    GPIO_PIN_12
#define EINK_VDD_PORT   GPIOB

#define VDD_OFF         GPIO_ResetBits  (EINK_VDD_PORT,   EINK_VDD_PIN)
#define VDD_ON          GPIO_SetBits    (EINK_VDD_PORT,   EINK_VDD_PIN)

#define PIC_YELLOW      253
#define PIC_RED          254
#define PIC_WHITE       255
#define PIC_BLACK       0
#define PIC_NULL        1
#define PIC_A            2
#define PIC_B            3
#define PIC_HLINE       4
#define PIC_HLINE1      10
#define PIC_VLINE       5
#define PIC_C            6
#define PIC_D            7
#define PIC_E            8
#define PIC_DOT          9

enum Vol_Value_e
{
    _2_3V = 0,
    _2_4V,
    _2_5V,
    _3_0V,
    _3_6V
};

#define SOURCE_SCAN_NUM (SOURCES/2)

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#define GATE_DIV_SET(x, num)      (GATES*x/num)
#define SOURCE_DIV_SET(y, num)    (SOURCE_SCAN_NUM*y/num)

static unsigned char Temptr = 0;

/*****
*Function-Delay Function (mS)
*Parameters-time: mS
*Back-void
*****/
void Delay_ms(int time)
// 1ms
{
    int i, j;

    for(i=0; i<time; i++)
        for(j=0; j<5375; j++);
}

/*****
*Function-Delay Function (S)
*Parameters-time: S
*Back-void
*****/
void Delay_S(int time)
// 1s
{
    int i, j, k;

    for(i=0; i<time; i++)
        for(j=0; j<800; j++)
            for(k=0; k<5375; k++);
}

/*****
*Function-IC Initialization Settings
*Parameters-void
*Back-void
*****/
void ReadBusy(void)
{
    while(1)
    {
        __NOP();
        if(BUSY_LEVEL != 0){
            break;
        }
    }
}

```

```

/*****
*Function-IC Reset Signal
*Parameters-void
*Back-void
*****/
void Reset(void)
{
    nRST_L;
    Delay_ms(20);
    nRST_H;
    Delay_ms(10);
    nRST_L;
    Delay_ms(20);
    nRST_H;
    Delay_ms(10);
    ReadBusy();
    Delay_ms(10);
}

/*****
*Function-IC_SPI Enter command
*Parameters-init_com: Command Code
*Back-void
*****/
void SPI4W_WriteCom(unsigned char init_com)
{
    unsigned char temp_com;
    unsigned char scnt;

    temp_com = init_com;
    nCS_H;
    nCS_L; //SPI
    chip select the signal, It will be active at a low level.
    SCLK_L;
    nDC_L;
    for(scnt=0; scnt<8; scnt++)
    {
        if(temp_com & 0x80)
            SDA_H;
        else
            SDA_L;
        SCLK_H;
        SCLK_L;
        temp_com = temp_com << 1;
    }
    nCS_H;
}

```

```

/*****
*Function-IC_SPI Enter data
*Parameters-init_data: Data Content
*Back-void
*****/
void SPI4W_WriteData(unsigned char init_data)
{
    unsigned char temp_data;
    unsigned char scnt;

    temp_data = init_data;
    nCS_H;
    nCS_L; //SPI
    chip select the signal, It will be active at a low level.
    SCLK_L;
    nDC_H;
    for(scnt=0;scnt<8;scnt++)
    {
        if(temp_data & 0x80)
            SDA_H;
        else
            SDA_L;
        SCLK_H;
        SCLK_L;
        temp_data = temp_data<<1;
    }
    nCS_H;
}

/*****
*Function-IC_SPI Read data
*Parameters-void
*Back-unsigned char one byte
*****/
unsigned char SPI4W_ReadData(void)
{
    unsigned char scnt,temp;

    gpio_cfg_input(EINK_SDA_PORT, EINK_SDA_PIN, PULLUP);

    nCS_H;
    nCS_L; //SPI
    chip select the signal, It will be active at a low level.
    //SCLK_H;
    SCLK_L;
    nDC_H;
    for(scnt=0; scnt<8; scnt++)
    {

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        //SCLK_H;
    if(SDA_LEVEL)
        temp = (temp<<1) | 0x01;
    else
        temp = temp << 1;
    //SCLK_H;
    SCLK_H;
    SCLK_L;
}
nCS_H;

    gpio_cfg_output(EINK_SDA_PORT, EINK_SDA_PIN, NOPULL);

    return temp;
}

```

```

/*****
*Function-Read the IC Temperature
*Parameters-void
*Back-unsigned char one byte
*****/
unsigned char ReadTemptr(void)
{
    unsigned char temptr_intgr = 0;
    unsigned char temptr_decml = 0;

    Reset();

    SPI4W_WriteCom(0x40);
    //Delay_S(1);
    Delay_ms(100);
    temptr_intgr = SPI4W_ReadData();
    temptr_decml = SPI4W_ReadData();

    Temptr = temptr_intgr;

    return temptr_intgr;
}

```

```

/*****
*Function-Read IC's Chip ID
*Parameters-void
*Back-unsigned char one byte
*****/
unsigned char Read_Revision(void)
{
    unsigned char rever[4]= {0};

```

```

Reset();

SPI4W_WriteCom(0x70);
rever[0] = SPI4W_ReadData(); //chip
id
rever[1] = SPI4W_ReadData();
//lut_ver[0:7]
rever[2] = SPI4W_ReadData();
//lut_ver[8:15]
rever[3] = SPI4W_ReadData();
//lut_ver[23:16]

return rever[0];
}

/*****
*Function-Send Display Command
*Parameters-None
*Back-None
*****/
void Display_Cmd(void)
{
    SPI4W_WriteCom(0x04); //
    Power ON
    ReadBusy();

    SPI4W_WriteCom(0x12); //
    Display Refresh
    SPI4W_WriteData(0x00);
    ReadBusy();

    SPI4W_WriteCom(0x02); //
    Power OFF
    SPI4W_WriteData(0x00);
    ReadBusy();
}

/*****
*Function-Enter Deep Sleep Mode
*Parameters-None
*Back-None
*****/
void EnterDeepsleep(void)
{
    SPI4W_WriteCom(0x07); //
    Deep sleep
    SPI4W_WriteData(0xA5);
}

```

```

/*****
*Functions—Basic Displays (the most common display content, such as font charts,
horizontal bars, vertical bars, full-color displays and others)
*Parameters- dis_type:Display Items
*Back- void
*****/
void Basic_Display(unsigned char dis_type)
{
    unsigned int col = 0, row = 0;
    unsigned int pcnt = 0;

    SPI4W_WriteCom(0x10); //
    DTMI_Write

    for(col=0; col<GATES; col++)
    {
        for(row=0; row<SOURCE_SCAN_NUM; row++)
        {
            switch(dis_type)
            {
                case PIC_A:
                    SPI4W_WriteData(gImage_Font[pcnt]);
                    break;

                case PIC_YELLOW:
                    SPI4W_WriteData(0x22);
                    break;

                case PIC_RED:
                    SPI4W_WriteData(0x33);
                    break;

                case PIC_BLACK:
                    SPI4W_WriteData(0x00);
                    break;

                default:
                case PIC_WHITE:
                    SPI4W_WriteData(0x11);
                    break;
            }
            pcnt++;
        }
    }

    Display_Cmd();
    return;
}

```

[illegible]

```

//xx  Main Function
xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx
//xxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxxx
int main(void)
{
    Sys_init();
    Delay_ms(200);           //System delay; waiting for VDD (3.0 V) to power on

    ReadTemptr();

    Reset();
    Init_IC();
    Basic_Display(PIC_WHITE);
    EnterDeepsleep();
    Delay_S(5);

    while (1)
    {

    };

}

```